

Computational Models — Lecture 13¹

Handout Mode

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June 15/17, 2015

¹Based on frames by Benny Chor, Tel Aviv University, modifying frames by Maurice Herlihy, Brown University.

Talk Outline

- ▶ Reminder - poly-time reductions, NP-completeness and SAT
 - ▶ SAT is NP-Complete
 - ▶ $SAT \leq_P 3SAT$
 - ▶ Hamiltonian Path Is NP-Complete
 - ▶ SUBSET-SUM Is NP-Complete
- Sipser, 7.4–7.5

Section 1

Reminder

Reminder – Poly-time Reductions

Definition 1

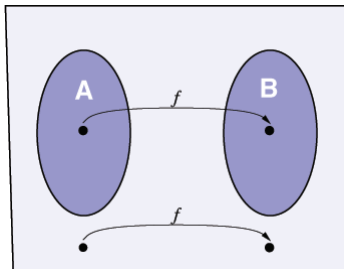
A language A is **poly-time mapping reducible** to B , denoted $A \leq_p B$, if exists poly-time computable function f such that

$$w \in A \iff f(w) \in B$$

for every $w \in \Sigma^*$.

The function f is called a **polynomial-time reduction** from A to B .

The mapping f **efficiently** converts questions about membership in A to membership in B .



Reminder – NP Completeness

Definition 2 (NP-complete)

A language B is **NP-complete**, if

- ▶ $B \in \mathcal{NP}$, and
- ▶ Every $A \in \mathcal{NP}$ is **poly-time** reducible to B

We let \mathcal{NPC} denote the class of all NP-complete languages.

$$A_{\text{NP}} = \{ \langle M, x, 1^n \rangle : M \text{ is a TM} \wedge \exists c \in \Sigma^* \text{ s.t. } M(x, c) \text{ accepts within } n \text{ steps} \}.$$

Theorem 3

$A_{\text{NP}} \in \mathcal{NPC}$.

Theorem 4

Assume that $B \in \mathcal{NP}$, $A \in \mathcal{NPC}$ and $A \leq_P B$, then $B \in \mathcal{NPC}$.

Boolean Formulas and SAT

A **Boolean** formula is an expression involving Boolean variables and operations.

$$\phi = (\bar{x} \wedge y) \vee (x \wedge \bar{z})$$

Definition 5 (satisfiable formula)

A formula is **satisfiable**, if some assignment of 0s and 1s to the variables makes the formula evaluate to 1.

The formula $\phi = (\bar{x} \wedge y) \vee (x \wedge \bar{z})$ is satisfiable by the assignment

$$x = 0$$

$$y = 1$$

$$z = 0$$

The language of satisfied formulas:

$$\text{SAT} = \{\langle \phi \rangle : \phi \text{ is a satisfiable Boolean formula}\}$$

Section 2

SAT is NP-Complete

$SAT \in \mathcal{NP}$

Theorem 6 (Cook-Levin, early 70s)

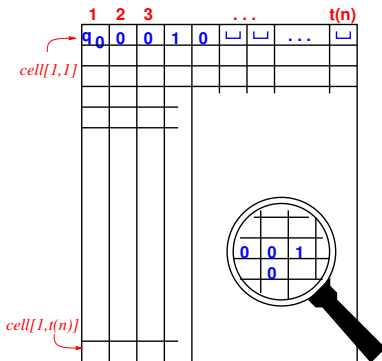
$SAT \in \mathcal{NP}$.

Proof's idea:

- ▶ Suppose $L \in \mathcal{NP}$ and let $N = (Q, \Sigma, \Gamma, \delta, q_0, q_a, q_r)$ be an n^c -time NTM that accepts L .
- ▶ Given the string $w \in \{0, 1\}^*$, construct in time $O(|w|^{2c})$ a formula $\phi_{N,w}$ such that: $\phi_{N,w} \in SAT$ iff N accepts w .
- ▶ Hence, the mapping $w \mapsto \phi_{N,w}$ is a poly-time reduction from L to SAT , establishing $L \leq_P SAT$.
- ▶ In the following fix L , N and $w \in \{0, 1\}^n$.
- ▶ We assume wlg. that $\delta(q_r, \cdot) = \emptyset$.

The Configuration-History Tableau

Consider the n^c -by- n^c **Tableau** that describes a **computation history** of N on input w .



- ▶ First row represents **initial configuration** of N on input w .
- ▶ i 'th row represents the i -th **configuration** in a **possible** computation of N on input w .

The formula $\phi_{N,w}$

- ▶ Let $S = Q \cup \Gamma$ (the alphabet of the configuration history).
- ▶ $\phi_{N,w}$ uses Boolean variables $\{x_{i,j,s}\}_{i,j \in [n^c], s \in S}$.

$$\phi_{N,w} = \phi_{\text{Cell}(N)} \wedge \phi_{\text{Start}(w)} \wedge \phi_{\text{Move}(N)} \wedge \phi_{\text{Accept}(N)}$$

- ▶ Given an assignment z for $\phi_{N,w}$, let $T(z)$ be the $n^c \times n^c$ Tableau, defined by setting the j -th cell in i 'th configuration to s , if $x_{i,j,s} = 1$ in z .
($T(z)$ is **undefined**, if $x_{i,j,s'} = x_{i,j,s} = 1$ for some $s \neq s' \in S$, or $x_{i,j,s'} = 0$ for all $s \in S$).
- ▶ $T(z)$ will represent a (possible) **accepting execution** of $N(w)$, iff z is an **satisfying assignment** for $\phi_{N,w}$.

The formula $\phi_{\text{Cell}(N)}$

$\phi_{\text{Cell}(N)}$ guarantees that the variables encode **legal** configurations:

- ▶ Each cell (i, j) has at least one letter: $\bigvee_{s \in S} x_{i,j,s}$.
- ▶ No cell (i, j) has two or more letters $\bigwedge_{s \neq s' \in S} \overline{x_{i,j,s} \wedge x_{i,j,s'}}$.

Together:

$$\phi_{\text{Cell}(N)} = \bigwedge_{i,j} \left[\left(\bigvee_{s \in S} x_{i,j,s} \right) \wedge \left(\bigwedge_{s \neq s' \in S} \overline{x_{i,j,s} \wedge x_{i,j,s'}} \right) \right]$$

Claim 7

If an assignment z satisfies $\phi_{\text{Cell}(N)}$, then $T(z)$ is defined.

The formula $\phi_{\text{Start}(w)}$

$\phi_{\text{Start}(w)}$ guarantees that the first row encodes the initial configuration (i.e., $q_0 w$).

$$\begin{aligned}\phi_{\text{start}(w)} = & X_{1,1,q_0} \wedge X_{1,2,w_1} \wedge X_{1,3,w_2} \wedge \dots \wedge X_{1,n+1,w_n} \\ & \wedge X_{1,n+2,\sqcup} \wedge \dots \wedge X_{1,n^c,\sqcup}\end{aligned}$$

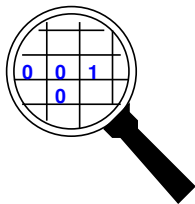
Claim 8

If z satisfies $\phi_{\text{Cell}(N)} \wedge \phi_{\text{Start}(w)}$, then the first line of $T(z)$ is $q_0 w \underbrace{\sqcup \dots \sqcup}_{n^c - n - 1}$.

The formula $\phi_{\text{Move}(N)}$

$\phi_{\text{Move}(N)}$ is the “heart” of $\phi_{N,w}$. To construct it, we employ **locality** of computations.

- ▶ To **verify** the content of Tableau entry (i, j) (i.e., cell j in configuration i), it only requires to know M 's table and the contents of the three Tableau entries: $(i - 1, j - 1)$, $(i - 1, j)$, $(i - 1, j + 1)$.



- ▶ If head not in area, **nothing changes**.
- ▶ If head is in area, changes are local and are **determined** by δ .

$\phi_{\text{Move}(N)}$ – Rectangles

A **rectangle** is a 2×3 configuration sub-table.

Assume that

$$\delta(q_1, a) = \{(q_1, b, R)\} \text{ and } \delta(q_1, b) = \{(q_2, c, L), (q_2, a, R)\}.$$

- ▶ (some) **Legal** 2×3 rectangles:

a	q_1	b
q_2	a	c

a	q_1	b
a	a	q_2

a	a	q_1
a	a	b

a	b	a
a	b	q_2

b	b	b
c	b	b

a	a	b
a	a	b

- ▶ (some) **Illegal** 2×3 rectangles:

a	b	a
a	a	a

a	q_1	b
q_1	a	a

b	q_1	b
q_2	b	q_2

$\phi_{\text{Move}(N)}$ – Characterizing legal rectangles

The formula “verifies” that all 2×3 rectangles in the Tableau are in the list C :

$\forall a, a', b, b', c \in \Gamma, q, q' \in Q$ and $*$ $\in S$, add the following rectangles to C :

1.

a	b	c
*	b	*

2.

a	q	b
q'	a	b'

a	q	b
a	b'	q'

$(L, q', b') \in \delta(q, b)$ $(R, q', b') \in \delta(q, b)$

3.

q	*	*
*	*	*

*	*	q
*	*	*

- Some rectangles in C are clearly illegal.
- For rectangles on the left-most and right-most side of Tableau, we use slightly different first type rectangles.

$\phi_{\text{Move}(N)}$ – formal definition

- ▶ For each entry $(i, j) \in [n^c] \times [n^c]$ and $c \in \mathcal{C}$, let $\phi_{\text{Move},i,j,c}$ be the formula taking the value 1 iff the 2×3 table of cells in the Tableau whose upper-left corner is (i, j) is c .

For instance, for entry $(1, 1)$ and $c =$

a	q_1	b
q_2	a	c

let $\phi_{\text{Move},1,1,c} = x_{1,1,a} \wedge x_{1,2,q_1} \wedge x_{1,3,b} \wedge x_{2,1,q_2} \wedge x_{2,2,a} \wedge x_{2,3,c}$

- ▶ Finally, let $\phi_{\text{Move}(N)} = \bigwedge_{(i,j)} \bigvee_{c \in \mathcal{C}} \phi_{\text{Move},i,j,c}$.

Claim 9

If z satisfies $\phi_{\text{Cell}(N)} \wedge \phi_{\text{Start}(w)} \wedge \phi_{\text{Move}(N)}$, then $T(z)$ is a **possible** configuration history of $N(w)$.

Proof: By induction on the row index. Base case: z satisfies $\phi_{\text{Cell}(N)} \wedge \phi_{\text{Start}(w)}$. Assume configuration defined in rows $1, \dots, i$ is possible and head is in cell j . The configuration of rows $1, \dots, i+1$ is also possible: Cells of indices **not** in $\{j-1, j, j+1\}$, by **first** type of rectangles in \mathcal{C} . Other cells, by **second** type rectangles in \mathcal{C} . **Q:** Why do we need the **third** type of cells?

The formula $\phi_{\text{Accept}(N)}$

$\phi_{\text{Accept}(N)}$ guarantees that some row encodes an accepting configuration (i.e., $uq_a v$):

$$\phi_{\text{Accept}(N)} = \bigvee_{i,j} x_{i,j,q_a}$$

Claim 10

If z satisfies $\phi_{N,w} = \phi_{\text{Cell}(N)} \wedge \phi_{\text{Start}(w)} \wedge \phi_{\text{Move}(N)} \wedge \phi_{\text{Accept}(N)}$, then $T(z)$ is an **accepting** configuration history of $N(w)$.

Correctness of reduction

- ▶ The transformation $w \mapsto \phi_{N,w}$ is computable in time $O(n^{2c})$.
- ▶ An assignment satisfying $\phi_{N,w}$, corresponds to an **accepting** configuration history of $N(w)$.
- ▶ An **accepting** configuration history of $N(w)$ corresponds to an assignment satisfying $\phi_{N,w}$. (?)

Therefore, N accepts w iff $\phi_{N,w} \in \text{SAT}$.



- ▶ For complete details, consult Sipser chapter 7.4.

Section 3

3SAT Is NP-Complete

CSAT and 3SAT

- ▶ $SAT = \{\langle \phi \rangle : \phi \text{ is a satisfiable Boolean formula}\}$
- ▶ A Boolean formula is in **conjunctive normal form** (CNF) if it consists of **clauses**, connected with \wedge 's.
For example: $(x_1 \vee \overline{x_2} \vee \overline{x_3} \vee x_4) \wedge (x_3 \vee \overline{x_5} \vee x_6) \wedge (x_3 \vee \overline{x_6})$
- ▶ $CSAT = \{\langle \phi \rangle : \phi \text{ is a satisfiable CNF formula}\}$
- ▶ One can slightly modify the proof of Cook-Levin theorem we just seen, to prove that $CSAT \in \mathcal{NP}$! (take home exercise :-))
- ▶ A Boolean formula is in **kCNF form**, if it is a **CNF** formula, and all clauses have **k** literals.
- ▶ $3SAT = \{\langle \phi \rangle : \phi \text{ is satisfiable 3CNF formula}\}$.
- ▶ Hence, to prove that $3SAT \in \mathcal{NP}$, it suffices to prove that $CSAT \leq_P 3SAT$.

CSAT \leq_P 3SAT

- ▶ The reduction maps CNF formulae to 3CNF ones “clause by clause”.
- ▶ A clause with $d \leq 3$ literals is mapped to **equivalent** clause with **3** literals.

$$(x_1 \vee x_2) \mapsto (x_1 \vee x_2 \vee x_2)$$

- ▶ A clause with $d > 3$ literals is mapped to d clauses, built on the original literals together with $(d - 3)$ new ones.

$$\phi = (x_1 \vee \overline{x_2} \vee \overline{x_3} \vee x_4 \vee x_8) \mapsto$$

$$\phi_3 = (x_1 \vee \overline{x_2} \vee y_1) \wedge (\overline{y_1} \vee \overline{x_3} \vee y_2) \wedge (\overline{y_2} \vee x_4 \vee x_8)$$

Claim 11

ϕ has a satisfying assignment iff ϕ_3 does.

Proof's idea: (for case $d > 3$)

\Leftarrow An assignment satisfying ϕ_3 cannot “rely” on new literals alone – at least one original literal must be satisfied.

\Rightarrow An assignment satisfying ϕ , makes at least one literal per clause **happy**. In the “ ϕ_3 clause” of this literal the new variable is under no constraints. This enables propagation to a satisfying assignment that “relies” on new vars alone in rest of ϕ_3 clauses.

CSAT \leq_P 3SAT, cont.

$$\phi = (x_1 \vee \bar{x}_2 \vee \bar{x}_3 \vee x_4 \vee x_8) \longmapsto$$

$$\phi_3 = (x_1 \vee \bar{x}_2 \vee y_1) \wedge (\bar{y}_1 \vee \bar{x}_3 \vee y_2) \wedge (\bar{y}_2 \vee x_4 \vee x_8)$$

- ▶ Doing the above mapping to **each** clause of a **CNF** formula, we get a **3CNF** that is satisfied iff the original one is.
- ▶ Since this mapping is polynomial time (?), we get **CSAT \leq_P 3SAT**. ♣.

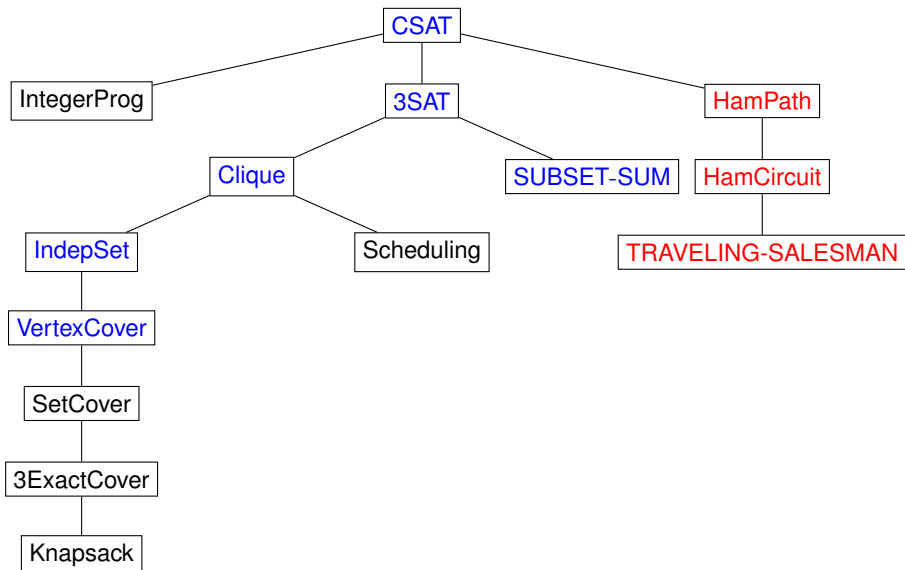
Section 4

Summary so far

Summary so Far

- ▶ We have seen that **SAT** and **CSAT** are NP-complete.
- ▶ **CSAT** \leq_P **3SAT**
- ▶ **3SAT** \leq_P **CLIQUE**
- ▶ **CLIQUE** \leq_P **IND-SET**
- ▶ In recitation: **CLIQUE** \leq_P **VC** (Vertex Cover), **IND-SET** \leq_P **PARTITION**, **PARTITION** \leq_P **BIN-PACKING**
- ▶ Hence, all of the above languages are NP-complete
- ▶ Full list of NP-complete languages contains hundreds or thousands of known NP-complete problems (from combinatorics, operation research, VLSI design, computational geometry, bioinformatics, ...).
- ▶ NP-completeness of new and of old problems is still established these days.

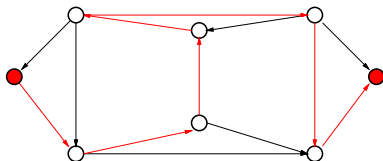
Chains of reductions: NPC languages



Section 5

Hamiltonian Path Is NP-Complete

(Directed) Hamiltonian path



A **Hamiltonian path** in a directed G visits each node **exactly** once.

$\text{HAMPATH} = \{ \langle G, s, t \rangle : G \text{ has Hamiltonian path from } s \text{ to } t \}$

- ▶ We have seen that $\text{HAMPATH} \leq_P \text{HAMCYCLE}$ and $\text{HAMPATH} \leq_P \text{TRAVELING-SALESMAN}$
- ▶ Will now show

Theorem 12

$\text{CSAT} \leq_P \text{HAMPATH}$

thus establishing

Theorem 13

$\text{HAMPATH}, \text{HAMCYCLE}, \text{TRAVELING-SALESMAN} \in \mathcal{NPC}$

CSAT \leq_P HAMPATH

For any CNF formula ϕ with clauses c_1, \dots, c_ℓ and variables x_1, \dots, x_k , we construct a directed graph G with vertices s and t , such that

ϕ is satisfiable iff \exists a directed Hamiltonian path from s to t .

Turn to a separate pdf presentation:

<http://tau-cm.wdfiles.com/local--files/course-schedule/ham-reduction-new.pdf>

Section 6

SUBSET-SUM Is NP-complete

Reminder — SUBSET-SUM

$$\text{SUBSET-SUM} = \{ \langle S = \{x_1, \dots, x_k\}, t \rangle : \exists \{y_1, \dots, y_m\} \subseteq S : \sum_{j=1}^m y_j = t \}$$

Example 14

- ▶ $\langle \{4, 11, 16, 21, 27\}, 25 \rangle \in \text{SUBSET-SUM}$ because $4 + 21 = 25$.
- ▶ $\langle \{4, 11, 16, 21, 27\}, 26 \rangle \notin \text{SUBSET-SUM}$
- ▶ Clearly $\text{SUBSET-SUM} \in \mathcal{NP}$.
- ▶ Will now show

Theorem 15

$3\text{SAT} \leq_P \text{SUBSET-SUM}$.

Thus establishing

Theorem 16

$\text{SUBSET-SUM} \in \mathcal{NPC}$.

$3SAT \leq_P \text{SUBSET-SUM}$

Let ϕ be 3-CNF a boolean formula with

- ▶ variables x_1, \dots, x_k
- ▶ clauses C_1, \dots, C_ℓ .

We “encode” ϕ into a set S containing $2k + 2\ell$ numbers in decimal notation, and a “target” number t , such that $\phi \in 3SAT \iff (S, t) \in \text{SUBSET-SUM}$

Variable encoding

Variable x_i is encoded as two $(k + \ell)$ -digit numbers: y_i and z_i .

Each decimal representation has two parts.

- ▶ Left-hand part, k digits: for both y_i and z_i , the i 'th digit is 1, rest are 0s
- ▶ Right-hand part, ℓ digits: one digit for each clause
 - ▶ j^{th} digit of y_i is 1 if C_j contains x_i
 - ▶ j^{th} digit of z_i is 1 if C_j contains \bar{x}_i
 - ▶ rest are 0s

Example: $\phi = (x_1 \vee \bar{x}_2 \vee \dots) \wedge \dots \wedge (\bar{x}_1 \vee \bar{x}_2 \vee \dots)$

	1	2	...	k	C_1	...	C_ℓ
y_1	1	0	...	0	1	...	0
z_1	1	0	...	0	0	...	1
y_2	0	1	...	0	0	...	0
z_2	0	1	...	0	1	...	1

Clause encoding

Each clause C_i is encoded into two equal $(k + \ell)$ -digit numbers: g_i and h_i . In both numbers, the $(k + i)$ 'th digit is 1 and rest are 0.

	1	...	k	C_1	C_2	...	C_ℓ
\vdots							
g_1	0	...	0	1	0	...	0
h_1	0	...	0	1	0	...	0
g_2	0	...	0	0	1	...	0
h_2	0	...	0	0	1	...	0

Target encoding

The target t is assigned the following $(k + \ell)$ -digit number

- ▶ first k digits are 1
- ▶ last ℓ digits are 3

	1	...	k	C_1	C_2	...	C_ℓ
\vdots							
t	1	...	1	3	3	...	3

Overall encoding

	1	2	...	k	C_1	C_2	...	C_ℓ
y_1	1	0	...	0	1	0	...	0
z_1	1	0	...	0	0	0	...	1
y_2	0	1	...	0	0	0	...	0
z_2	0	1	...	0	1	0	...	1
\vdots								
g_1	0	0	...	0	1	0	...	0
h_1	0	0	...	0	1	0	...	0
g_2	0	0	...	0	0	1	...	0
h_2	0	0	...	0	0	1	...	0
\vdots								
t	1	1	...	1	3	3	...	3

$$S = \{y_1, z_1, y_2, z_2, \dots, y_k, z_k, g_1, h_1, g_2, h_2, \dots, g_\ell, h_\ell\}.$$

Transformation takes $O(n^2)$ time.

ϕ is satisfiable $\implies (S, t) \in \text{SUBSET-SUM}$

Given satisfying assignment to ϕ , construct **initial** solution V to (S, t) as follows: If $x_i = 1$, add y_i to V ; otherwise, add z_i to V .

- ▶ Each of the **first** k digits of $\sum_{v \in V} v$ is **1** (as in t)
- ▶ For $1 \leq j \leq \ell$, consider the $(k + j)$ 'th digit of $\sum_{v \in V} v$:
 - ▶ **at least 1** and **not more** than **3** literals in C_j are **1**
 \implies the $(k + j)$ 'th digit is between **1** and **3**.
 - ▶ Add "enough" $\{h_i, g_i\}$ to V to bring this digit up to **3**.
(Doing this does **not** effect the other digits of $(\sum_{v \in V} v)$).

Hence, $\sum_{v \in V} v = t$. ♣

$(S, t) \in \text{SUBSET-SUM} \implies \phi$ is satisfiable

Given a solution V to (S, t) .

1. Summation causes **no carries**
 - ▶ All digits in the numbers of S are either **0** or **1**.
 - ▶ Since ϕ is in **3CNF**, each "column" contains at most **five 1s**.
2. For each $i \in [k]$, the subset V contains **one** of y_i or z_i , but **not both**.
3. For each $i \in [\ell]$, the subset V contains **at least** one element of $\{y_1, z_1, \dots, y_k, z_k\}$ whose $(k + i)$ 'th bit is **1**:
 - ▶ Each of final ℓ "columns" sums to **3**.
 - ▶ The set $\{g_j, h_j\}$ contributes at most **2**
 - ▶ So at least one must come from literal taking the value **1**

The satisfying assignment.

For $i \in [k]$: if $y_i \in V$, set $x_i = 1$; otherwise, set $x_i = 0$.

The assignment satisfies ϕ because all clauses are satisfied (see **Item 3**)



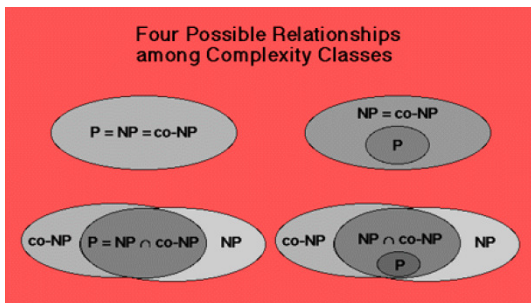
Section 7

Concluding Remarks

Ladies and Gentlemen, Boys and Girls

We have just ended the third part of the course:

Introduction to Computational Complexity (no more).



And with it, naturally, we've ended the whole course.

We hope you have enjoyed your flight, and look forward to meeting you in the future (**but not in Moed B** :-).

The dreaded exam

- ▶ All material covered in class and recitations, from all parts of course.
- ▶ Five “open” questions.
- ▶ You can bring and use two double sided A4 (normal size) pages marked with your name.
- ▶ See website for more info.
- ▶ Piece of cake.

